



Hyperbolic Geometry - 1

Main Ref: << An Introduction to Geometric Topology >> Marcell;

• Roughly speaking, there are "three" kind of geometries in Riemannian geometry: S^n , \mathbb{R}^n , H^m , responding to the unique simply connected, complete, Riemannian manifold with constant sectional curvature 1, 0, -1 (positive, flat, negative)

In this seminar, I will introduce several Hyperbolic model. I will list them as below. They have different advantages and drawbacks, we will use one of them as long as it is convenient.

	Model name	advantage
1:	Hyperboloid	easy to calculate
	↓ (projection)	
2:	Poincaré disk	easy to see
	↓ (inversion)	
3:	Half plane model	has a nice ∞
	↓	
4:	Klein model	geodesics are "lines" (easy to see)

And we will follow the path above to study them. In each model, we will care about

- ① How does they look like?
- ② What is the subspace? (geodesically submanifold)
- ③ the metric tensor calculation.
- ④ Some geometric properties.



§ 1 Hyperboloid model. (I^n)

Recall how we get S^n ? From Euclidean inner product $\langle x, y \rangle_E := \sum_{i=1}^n x_i y_i = 1$. So we can generalize this thing. Firstly, we give the defn of "scalar product"

Def 1 (Scalar product)

symmetric.

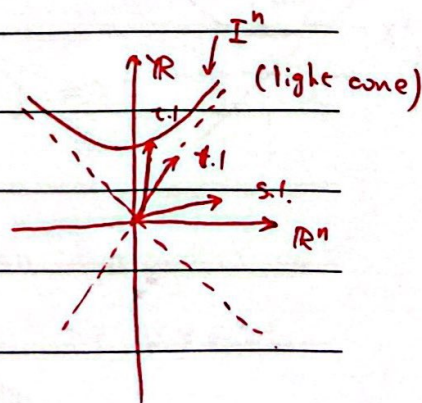
Let V be an vector space. $\langle \cdot, \cdot \rangle$ is a bilinear form and nondegenerate. We call it is a scalar product with signature (p, q) . ($p+q = \dim V$) if it can be represented by $\begin{pmatrix} I_p & 0 \\ 0 & -I_q \end{pmatrix}$ for some special basis.

In \mathbb{R}^{n+1} , $\langle x, y \rangle_L := \sum_{i=1}^n x_i y_i - x_{n+1} y_{n+1}$ is called the Lorentzian scalar product. its signature is $(n, 1)$. $\langle x, y \rangle_E := \sum_{i=1}^{n+1} x_i y_i$ is the traditional inner product. its --- is $(n+1, 0)$.

Def 2 (Hyperboloid I^n)

$$I^n := \{ x \in \mathbb{R}^{n+1} \mid \langle x, x \rangle_L = -1, \underline{x_{n+1} > 0} \}$$

- time-like vector, if $\langle x, x \rangle_L < 0$
- light-like vector, if $\langle x, x \rangle_L = 0$
- space-like vector, if $\langle x, x \rangle_L > 0$.





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Naive Question: Does I^n is a mfd? Riemann mfd?

Prop 3: For any scalar product $\langle \cdot, \cdot \rangle$ on \mathbb{R}^{n+1} , The function

$f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ given by $f(x) = \langle x, x \rangle$ is everywhere

smooth and has differential, $\forall y \in T_x \mathbb{R}^{n+1} \cong \mathbb{R}^{n+1}$

$$f_{*x}(y) = 2\langle x, y \rangle.$$

If: consider $r(t) = x + ty$. then

$$f_{*x}(y) = f_{*x}(r'(0)) = \left. \frac{d}{dt} \right|_{t=0} f(r(t))$$

$$= \left. \frac{d}{dt} \right|_{t=0} \langle x + ty, x + ty \rangle = 2\langle x, y \rangle. \quad \square$$

Corollary 4 I^n is a Riemannian mfd.

If: ① Since $\langle \cdot, \cdot \rangle_L$ is nondegenerate $\Rightarrow f_*$ is surjective \Rightarrow

-1 is the regular value of f . $\Rightarrow I^n$ is a mfd.

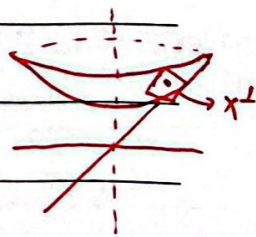
② To check I^n is a Riemannian mfd

That's why we first introduce this model.

Step 1: what is the tangent space?

$$T_x I^n = \ker f_{*x} = \{y \mid \langle x, y \rangle_L = 0\} := x^\perp$$

(this is really similar to S^n !!) \rightarrow (level set)



because the tangent space has a nice

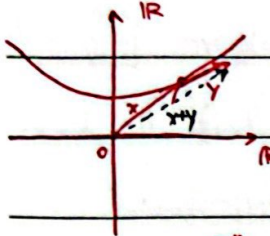
Step 2: what is the metric tensor \Leftrightarrow Find an inner product on x^\perp .

straightforward **Claim:** $\langle \cdot, \cdot \rangle_L|_{x^\perp}$ gives an inner product. i.e. $\forall y \in x^\perp$.

expression! $\langle x, y \rangle_L \geq 0$, and $= 0$ iff $y = 0$.



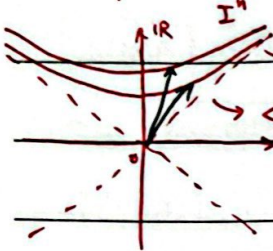
Pf of claim: (Note that $\langle x, y \rangle_L = 0$ although they are not look like "or-")



Goal: $\langle y, y \rangle_L \geq 0$. consider $\langle x+y, x+y \rangle_L$.

\Leftrightarrow pf: $\langle x+y, x+y \rangle_L \geq \langle x, x \rangle_L$.

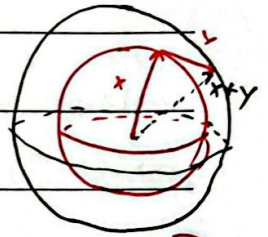
observation: $x+y$ lies below the I^n !!



$\langle \cdot, \cdot \rangle_L = a \Rightarrow \langle x+y, x+y \rangle_L \geq \langle x, x \rangle_L$
 $\langle \cdot, \cdot \rangle_L = b$

$\langle \cdot, \cdot \rangle_L = 0$. Then we finish!!

(check the verison of sphere!)



Exercise: For different scalar product $\langle \cdot, \cdot \rangle$, $\langle x, x \rangle = c$

diffeomorphic iff signature same

Now we study the Isometries of I^n .

Defns: $f: I^n \rightarrow I^n$ is called an Isometry if

① it is a diffeomorphism.

② $\forall x \in I^n, u, v \in T_x I^n, \langle f_{*x}(u), f_{*x}(v) \rangle_L = \langle u, v \rangle_L$

a Riemannian Exercise.

$\Leftrightarrow \forall p, q \in I^n, \langle f(p), f(q) \rangle_L = \langle p, q \rangle_L$

$\Leftrightarrow \langle Ax, Ay \rangle_L = \langle x, y \rangle_L$

Thm b: $\text{Isom}(I^n) = O^+(n, 1) = \{A \mid A^T \begin{pmatrix} I_n & 0 \\ 0 & -1 \end{pmatrix} A = \begin{pmatrix} I_n & 0 \\ 0 & -1 \end{pmatrix}, A \text{ preserve the upper half}\}$.

这两个数注

(\Leftarrow) trivial $O^+(n, 1) \subset \text{Isom}(I^n)$

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(\Rightarrow) We will use a fact from Riemannian mfd: If M, n

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are connected Riemannian mfd, f, g are the isometries, $f(p) = g(p)$.

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$f_{*p} = g_{*p}$ then $f = g$. Thus we only need to find any $f \in \text{Isom}(I^n)$.

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Find a matrix $A \in O^+(n, 1)$ and some $p \in I^n$

① $f(p) = A(p)$ ② $f_{*p} = A$. \rightarrow then $f = A$



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Now we have $f \in \text{Isom}(I^n)$ is arbitrary. How to find A ?

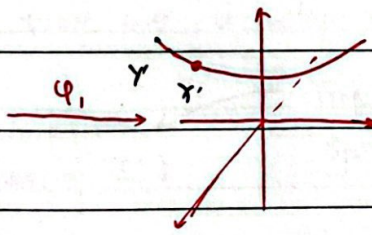
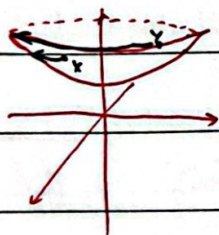
Step 1 specialize f . we also need to find some p . we also need to find a special p . \rightarrow chose $x_0 = (0, \dots, 0, 1)$. and $x_1 := f(x_0)$.

~~$\exists p, f(p) = x_0$ (f is diffeomorphism).~~

LEMMA: $O^+(n,1)$ acts transitively on I^n \leftrightarrow thus we can transform $x_1 \rightarrow x_0$.

Key observation: we can rotate first n -coordinate. i.e. $(A, 1) \in O(n)$

$\in O^+(n,1)$. For any $x, y \in I^n$. $\exists \varphi_1 \in O^+(n,1)$. such that think sphere



$$x' = (x_1, \dots, 0, x_{n+1}), y' = (y_1, \dots, 0, y_{n+1})$$

$$\text{then we have } x_1^2 - x_{n+1}^2 = -1$$

$$y_1^2 - y_{n+1}^2 = -1$$



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Let $x_1 = \sinh t_1, x_{n+1} = \cosh t_1, y_1 = \sinh t_2, y_{n+1} = \cosh t_2$, we have another

$$\text{rotation: } \begin{pmatrix} \cosh(t_2 - t_1) & 0 & \sinh(t_2 - t_1) \\ 0 & I_{n-2} & 0 \\ \sinh(t_2 - t_1) & 0 & \cosh(t_2 - t_1) \end{pmatrix} := \varphi_2. \text{ 双曲旋转.}$$

sends x' to y' (Direct calculation) \square

启发: 将双曲线视为大圆!! (类似 S^n)

Now consider $\psi \in O^+(n,1)$. and $\psi(x_1) = x_0$. so we have

$$\psi \circ f \in \text{Isom}(I^n). \quad \psi \circ f(x_0) = x_0. \quad \rightarrow T_{x_0} I^n = \{(x, \dots, x_n, 0)\}$$

Step 2: suppose $(\psi \circ f)_* x_0 = B$. then $B \in O(n)$. (direct calculation)

\Rightarrow chose $C = (B, 1) \in O^+(n,1)$. then

$$\textcircled{1} (\psi \circ f)_* x_0 = C_* x_0 = C. \quad \textcircled{2} \psi \circ f(x_0) = x_0 = C(x_0) = x_0.$$

$$\Rightarrow \psi \circ f = C \Rightarrow f = \psi \circ C \in O^+(n,1)! \quad \square$$



Rmk: $O(n) \subseteq O^+(n,1)$. We have not an explicit formula of $O^+(n,1)$.
 So we still not know the explicit Isometry group. Actually they are quite complicated. We will only talk about the lower dimension isometry group.

Now we introduce the "subspaces" of I^n . More precisely we will define some subflds of I^n directly. And then we will show that they are actually geodesically.

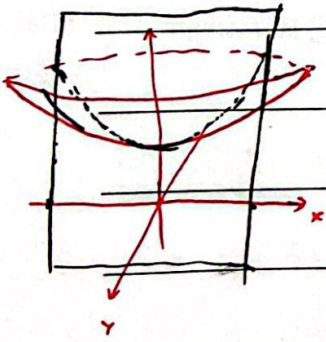
↙ You can view it as some special subflds if you have not ready $\mathbb{R}G$.

Defn 1 (subspaces of I^n)

A k -dimensional subspace of I^n is the intersection of a

$(k+1)$ -dimensional vector subspace of \mathbb{R}^{n+1} with I^n . does not contain

↘ contain origin!!!! We will only say "affine" if it

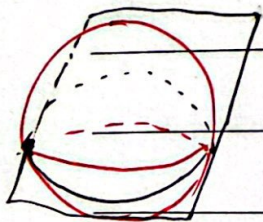


Rmk: For $k+1$ -vector subspaces $W \subseteq \mathbb{R}^{n+1}$ Following are Eq..

- ① $W \cap I^n \neq \emptyset$
- ② W contains at least a time-like vector
- ③ the signature of $\langle \cdot, \cdot \rangle_W$ is $(k,1)$.

Let $W \cap I^n = S$. then $\forall x \in S, T_x S \subseteq W$. $\xrightarrow{k \text{ dim}}$

we can choose $\{x, T_x S\}$ as a basis of W .





From the rnk. we have an important corollary:

Corollary 8 A k -subspace of I^n is itself isometric to I^k .

The non-empty intersection of two subspaces is always a subspace.

An isometry of \mathbb{R}^n, I^n sends k -subspace to k -subspace

Defn 9 (lines) A 1-subspace is a line, i.e. a 2-vector subspaces intersection with I^n .

(the line in \mathbb{R}^n are the line, the line is the S^1 are the big circle, the line in I^n are the hyperbolic lines).

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Now we talk about the geodesics. We can a $\gamma(t) \subseteq M^n \subseteq \mathbb{R}^n$

is a geodesic if ① $\gamma(t) \subseteq M^n$ ② $\langle \dot{\gamma}(t), \dot{\gamma}(t) \rangle = 1$. ③ $\ddot{\gamma}(t)$ projects

to the tangent space are zero. ④ $\ddot{\gamma}(t)$ projects to the tangent space are zero.

$\langle v, v \rangle_E = 1, \langle v, v \rangle_C = 1$

Thm 10: let $p \in M$ be a point and $V \in T_p M$ a "unit" vector

The geodesic γ exiting from p with velocity V is

- $\gamma(t) = p + tV$ if $M = \mathbb{R}^n$
- $\gamma(t) = \cos t \cdot p + \sin t \cdot V$ if $M = S^1$
- $\gamma(t) = \cosh t \cdot p + \sinh t \cdot V$ if $M = I^n$.



Pf: We take I^n as an example. What we need to show?

① $r(t) \subseteq I^n \Leftrightarrow \langle r(t), r(t) \rangle_L = -1$

$\langle \cosh t \cdot p + \sinh t \cdot v, \cosh t \cdot p + \sinh t \cdot v \rangle_L = (\cosh t)^2 \cdot (-1) + (\sinh t)^2 \cdot (-1) = -1$

② $\dot{r}(t) = \sinh t \cdot p + \cosh t \cdot v$ is unit speed vector.

$\langle \dot{r}(t), \dot{r}(t) \rangle = -\sinh^2 t + \cosh^2 t = 1$.

③ $\ddot{r}(t) = \cosh t \cdot p + \sinh t \cdot v = r(t)$. $r(t) \perp T_{r(t)} I^n \Rightarrow \checkmark$.

Then $r(t)$ is the geodesic.

Thm 11 aff geodesics \Leftrightarrow lines.

• From linearity \Rightarrow lines are geodesics $\cosh t \cdot p + \sinh t \cdot v \subseteq W$.

• Suppose $W = \text{span}\{p, v\}$, then we need to check

$W \cap I^n = \{ \cosh t \cdot p + \sinh t \cdot v \}$.

" \supseteq " is trivial.

" \subseteq " we need to parameterize the $W \cap I^n$. $\forall q \in W \cap I^n$, we

can use $\sigma^{(n,1)}$ to find $l = W \cap I^n \rightarrow x_i^2 - x_{n+1}^2 = -1$.

$\rightarrow \sinh t, \cosh t$ -- we can easily -- □

Prop 12 Let $p, q \in M$. We have

• $M = S^n$. $\cos(d(p, q)) = \langle p, q \rangle_E$

• $M = I^n$. $\cos(d(p, q)) = -\langle p, q \rangle_L$.